



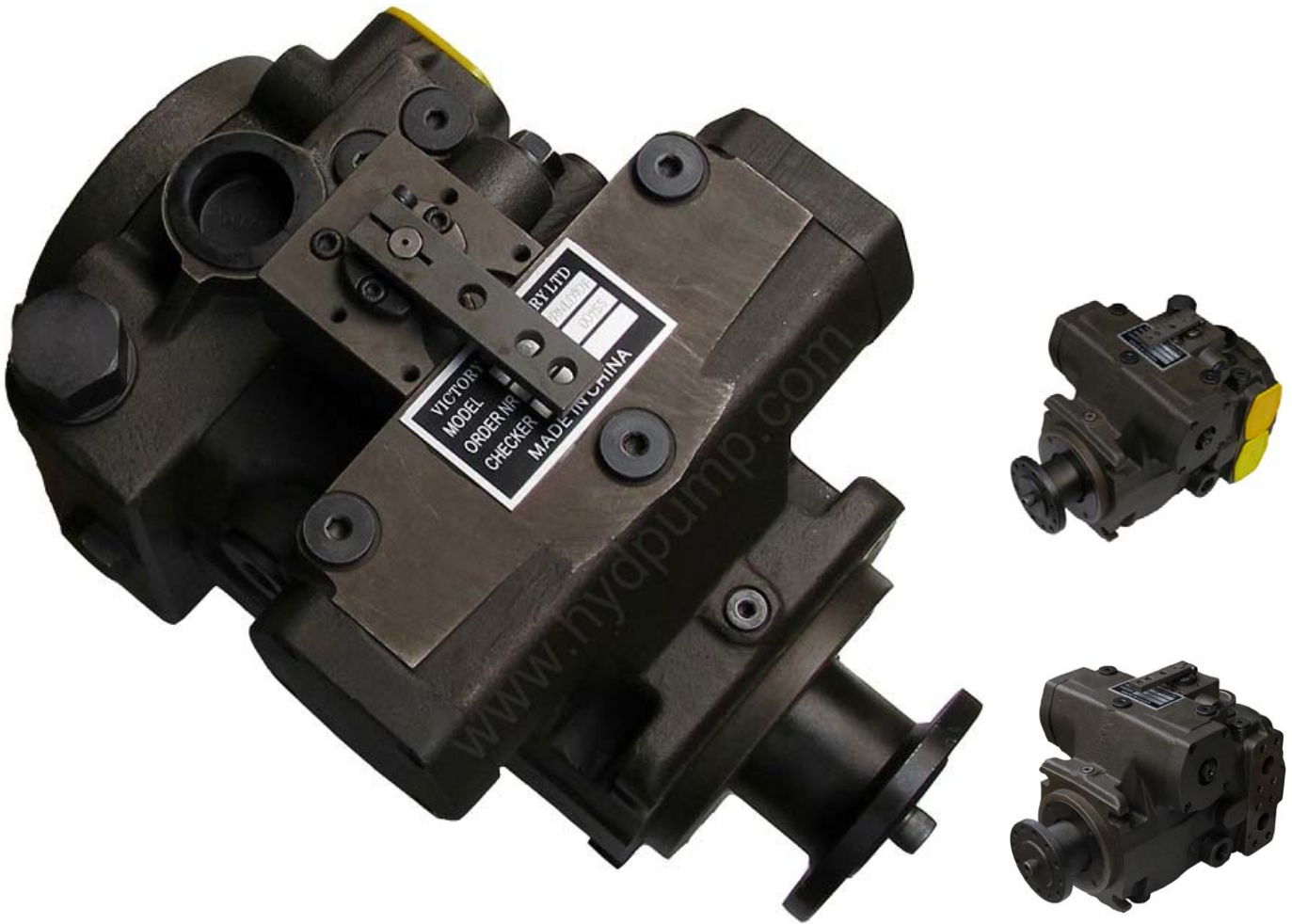
## Variable Displacement Mannesmann Rexroth A4VTG Pump

A4VTG90HW/32R-NLD10F001S-S (2023675)

for Drum Drives on Mobile Concrete Mixers Series 3, axial piston swash plate design

Nominal pressure 400 bar

Peak pressure 450 bar



### Table of values

Size		71	90	
Displacement	Variable pump	$V_{g \max}$ cm <sup>3</sup>	71	90
	auxiliary pump	$V_{gH}$ cm <sup>3</sup>	18,7	25,7
Speed	max. speed at $V_{g \max}$	$n_{\max \text{continuous}}$ rpm	3300	3050
	limited max. speed	$n_{\max \text{limited}}$ rpm	3600	3300
	intermittent max. speed	$n_{\max \text{intermittend}}$ rpm	4100	3800
	minimum speed	$n_{\min}$ rpm	500	500
Flow	at $n_{\max \text{Dauer}}$ and $V_{g \max}$	$Q_{\max}$ L/min	234	275
Power	at $n_{\max \text{Dauer}}$ p = 400 bar	$P_{\max}$ kW	156	183
Torque	at $V_{g \max}$ p = 400 bar	$T_{\max}$ Nm	451	572
	(Variable pump without aux.pump) p = 100 bar	T Nm	112,8	143
Moment of inertia (about drive axis)		J	0,0072	0,0106

**Technical Data**

**Operating pressure range – outlet**

Variable displacement pump:

Pressure at ports A, B

Nominal pressure  $p_N$  \_\_\_\_\_ 400 bar

Peak pressure  $p_{max}$  \_\_\_\_\_ 450 bar

Auxiliary pump:

Peak pressure  $p_{H max}$  \_\_\_\_\_ 40 bar

**Operating pressure range – inlet (auxiliary pump):**

Suction pressure  $p_{s min}$  ( 30 mm<sup>2</sup>/s) \_\_\_\_\_ 0,8 bar abs.

at cold start \_\_\_\_\_ 0,5 bar abs.

(Pressure data to DIN 24312)

**Case drain pressure**

Permissible case drain pressure at ports  $T_1$  or  $T_2$

$p_L$  \_\_\_\_\_ 2 bar abs.

short term (at start) \_\_\_\_\_ 3 bar abs.

**Fluid**

We request that before starting a project detailed information about the choice of pressure fluids and application conditions are taken from our catalogue sheets RE 90220 (mineral oil), RE 90221 (environmentally acceptable hydraulic fluids) and RE 90223 (fire resistance fluids, HF).

**Operating viscosity range**

In order to obtain optimum efficiency and service life, we recommend that the operating viscosity (at operating temperature) be selected from within the range:

$$n_{opt} = \text{Operating Viscosity } 16...36 \text{ mm}^2/\text{s}$$

referred to the closed loop temperature.

**Viscosity limits**

The limiting values for viscosity are as follows:

$$n_{min} = 5 \text{ mm}^2/\text{s}, \text{ short term at a max. permissible temp. of } t_{max} = 115 \text{ C.}$$

Please note that the max. fluid temperature of 115 C is not exceeded in certain areas (for instance bearing area).

$$n_{max} = 1600 \text{ mm}^2/\text{s}, \text{ short term on cold start } (t_{min} = -40 \text{ C}).$$

At temperatures of -25 C up to -40 C special measures may be required for certain installation positions. Please contact us for further information.

**Filtration**

The finer the filtration the better the achieved purity grade of the pressure fluid and the longer the life of the axial piston unit. To ensure the functioning of the axial piston unit a minimum purity grade of:

9 to NAS 15, 38

6 to SAE, ASTM, AIA

18/15 to ISO/DIS 4406 is necessary.

In this case we recommend, depending on system and application filter element 20 ... 30 100

for the A4VTG. With the rising differential pressure at the filter element the  $\Delta p$ -value must **not** decrease.

At very high temperatures of the hydraulic fluid (90 C to max. 115 C) at least cleanliness class

8 to NAS 1638

5 to SAE, ASTM, AIA

17/14 to ISO/DIS 4406 is necessary.

If above mentioned grades cannot be maintained please consult supplier.

**Standard: Filtration in the suction line of the auxiliary pump, S**

Filter type: \_\_\_\_\_ Filter **without** bypass

Recommendation: \_\_\_\_\_ **with** contamination indicator

Resistance to flow at the filter element:

at  $n = 30 \text{ mm}^2/\text{s}, n = n_{max}$  \_\_\_\_\_  $p$  0,1 bar

at  $n = 1000 \text{ mm}^2/\text{s}, n = 1000 \text{ rpm}$  \_\_\_\_\_  $p$  0,3 bar

Pressure at port S of the auxiliary pump:

at  $n = 30 \text{ mm}^2/\text{s}$  \_\_\_\_\_  $p$  0,8 bar

at cold start \_\_\_\_\_  $p$  0,5 bar

**Table of values** (Theoretical values, not considering  $n_{mh}$  and  $v_f$ ; values rounded)

Size				71	90	
Displacement	Variable pump	$V_{g max}$	cm <sup>3</sup>	71	90	
	auxiliary pump	$V_{g H}$	cm <sup>3</sup>	18,7	25,7	
Speed	max. speed at $V_{g max}$	$n_{max continuous}$	rpm	3300	3050	
	limited max. speed <sup>1)</sup>	$n_{max limited}$	rpm	3600	3300	
	intermittent max. speed <sup>2)</sup>	$n_{max intermittend}$	rpm	4100	3800	
	minimum speed	$n_{min}$	rpm	500	500	
Flow	at $n_{max Dauer}$ and $V_{g max}$	$Q_{max}$	L/min	234	275	
Power	at $n_{max Dauer}$	$p = 400 \text{ bar}$	$P_{max}$	kW	156	183
Torque	at $V_{g max}$	$p = 400 \text{ bar}$	$T_{max}$	Nm	451	572
	(Variable pump without aux. pump)	$p = 100 \text{ bar}$	$T$	Nm	112,8	143
Moment of inertia (about drive axis)		$J$	kgm <sup>2</sup>	0,0072	0,0106	
Weight (standard model without through drive) approx.		$m$	kg			

<sup>1)</sup> limited max. speed: – at half corner power (e.g. at  $V_{g max}$  and  $p_N / 2$ )

<sup>2)</sup> intermittent max speed: – at high idling speed – during engine overspeed:  $p = 70 \dots 150 \text{ bar}$  and  $V_{g max}$   
– with reversing heads:  $p < 300 \text{ bar}$  and  $t < 5 \text{ sek.}$

**Ordering Code**

**A4VT G 90 HW / 3 2 R - N L D 10 F00 1 S**

**Axial piston pump**

Swashplate design, variable displacement for drum drives on mobile concrete mixers **A4VT**

**Operation**

Pump, closed circuit **G**

**Size**

$\Delta$  Displacement  $V_{g \max}$  in  $cm^3$  **71 90**

**Control device**

	71	90	
Hydraulic control, mechanical servo	HW	<input type="radio"/>	<input type="radio"/> <b>HW</b>
Electrical control, with proportional solenoid	12V	<input type="radio"/>	<input type="radio"/> <b>EP1</b>
	24V	<input type="radio"/>	<input type="radio"/> <b>EP2</b>

**Series**

**3**

**Index**

**2**

**Direction of rotation**

viewed on shaft end clockwise **R**  
anti-clockwise **L**

**Seals**

NBR (nitril-caoutchouc) **P**  
 NBR, shaft seal in FPM (fluor caoutchouc) **N**

**Shaft end**

Splined shaft SAE, without coupling flange **S**  
 with coupling flange **L**

**Mounting flange**

SAE C, 4-hole **D**

**Service ports**

Port A/B SAE, (metric fixing screws), at side (same side) **10**

**Auxiliary pump and through drive**

auxiliary pump	splined hub	through drive	flange	
<input type="radio"/>	-	-	-	<b>F00</b>
<input type="radio"/>	SAE A (5/8" - 9T 16/32 DP)	SAE A, 2-hole		<b>F01</b>
<input type="radio"/>	SAE B (7/8" - 13T 16/32 DP)	SAE B, 2-hole		<b>F02</b>

**Valves**

with high pressure relief valve, pilot controlled (fixed setting 420 bar) with bypass **1**

**Filtration**

Filtration in the suction line of the auxiliary (boost) pump **S**

● ○

**Installation position**

Optional. The housing must be filled prior to commissioning, and must remain full whenever it is operating. For extensive information on the installation position, please read our data sheet RE 90270.

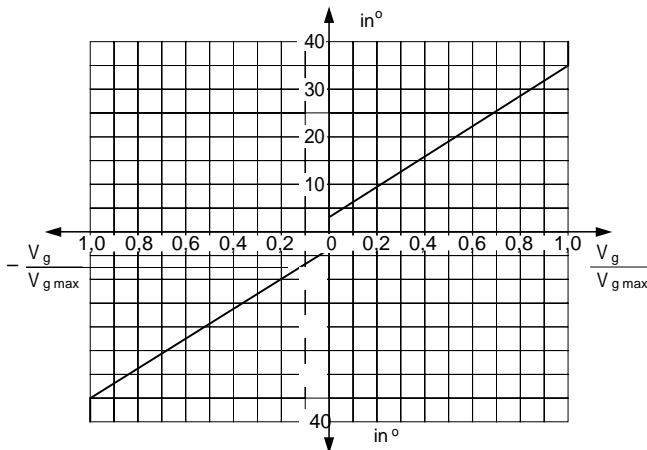
**Temperature range of the radial seal rings**

The following radial seal rings are to be used in relation of the housing temperature:

- 40 C ... -25 C NBR radial seal ring necessary (P);
- 25 C ... +90 C NBR radial seal ring standard (P),  
 FPM radial seal ring possible (N);
- +90 C ... +115 C FPM radial seal ring necessary (N).

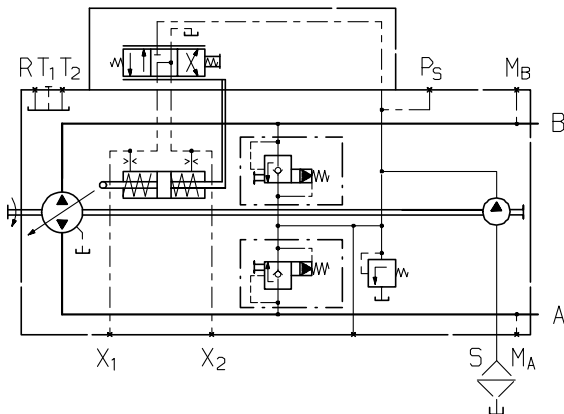
### HW Hydraulic control, mechanical servo

The positioning cylinder of the pump and therefore the swivel angle is varied in proportion to the movement of the control lever. The pump control is steplessly variable. Each direction of flow is assigned to one direction of lever movement.



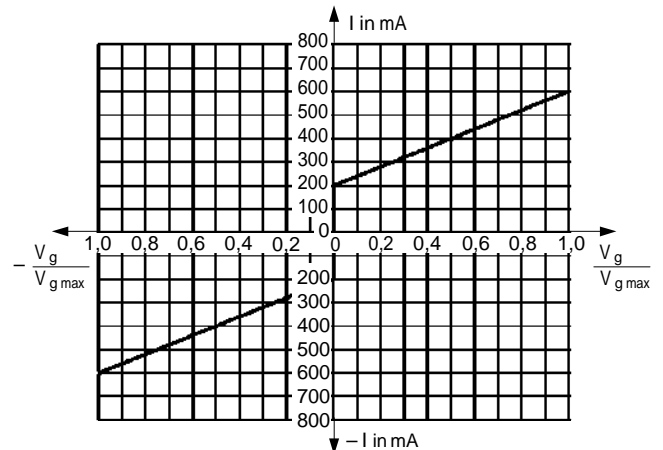
Swivel angle of control lever for swivel from 0 to  $V_{g \max}$ :  
= 0 to 35°, mechanical stop at

Torque necessary at control lever is between 85 and 210 Ncm  
Dependant from the operation conditions of the pump (operation pressure, oil temperature) changes of the curve can occur.



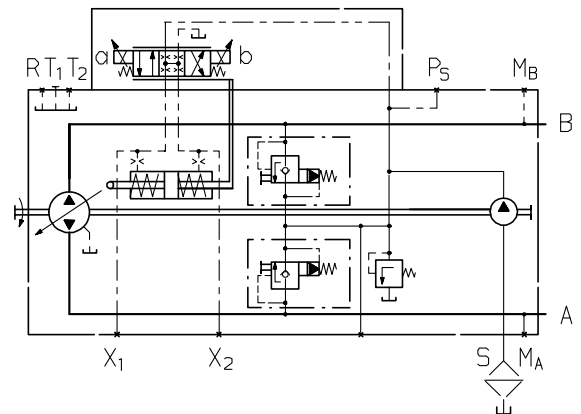
### EP Electrical control, with proportional solenoids

In relation to the preselected current, control pressure is applied to the positioning cylinder of the pump via two proportional solenoids on control device EP. The displacement of the pump is thus steplessly variable. One solenoid is assigned to each direction of flow.

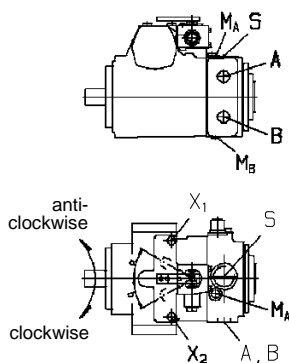


**EP2:** Control current  $I = 200 - 600$  mA  
(24V DC proportional solenoids)

**EP1:** Control current  $I = 400 - 1200$  mA  
(12V DC proportional solenoids)



For control of the proportional solenoids are available:  
Chopper amplifier **CV** \_\_\_\_\_ (see RE 95029),  
proportional amplifiers **PVR, PVRs** \_\_\_\_\_ (see RE 95022)  
electronic control for reversing drives **RVR** \_\_\_\_\_ (see RE 95031)  
constant speed drive **CSD** \_\_\_\_\_ (see RE 95075)



**Graph Direction of rotation - Control - Direction of through flow**

Direction of rotation	clockwise		anti-clockwise	
Lever direction (HW)	a	b	a	b
Solenoid (EP)	b	a	b	a
Control pressure	X <sub>2</sub>	X <sub>1</sub>	X <sub>2</sub>	X <sub>1</sub>
Direction of flow	A to B	B to A	B to A	A to B
Operating pressure	M <sub>B</sub>	M <sub>A</sub>	M <sub>A</sub>	M <sub>B</sub>

